Citizen Science and UAVs: How to monitor the Victorian coast

Nicolas Pucino¹, Rafael C. Carvalho¹, Blake Allan¹, David M. Kennedy², Daniel Ierodiaconou¹

¹ School of Life and Environmental Sciences, Deakin University, <u>npucino@deakin.edu.com</u> ² School of Geography, Faculty of Science, The University of Melbourne











Environment Land, Water and Planning

Dan



From: Daniel lerodiaconou <<u>daniel lerodiaconou@deakin.edu.au</u>> Sent: Tuesday, March 27, 2018 2:16:41 PM To: Nicolas Pucino Subject: RE: junior architect opportunities

Dear Nicolas, completely understand and wish you and your partner all the best in the future.

I would suggest if you are keen on the project that you apply anyway. We really have no idea what applicants we will get and whilst not ideal the steering committee may consider an alternate location. The key for them is that we secure the best candidates to grow the program

Key is to make it very clear in the cover letter. Make sure also that you address the selection criteria. As you are aware we also have a campus in Melbourne and Geelong with a research station at Queenscliffe that could also be an option if the Geelong (big town) area is of interest. There is a push to have more marine and coastal postdocs at Queencliffe.

Thanks for the kinds words. Hopefully if you meet me in person you feel the same!

Family is the most important thing Nicolas- if you keep that the focus my experience is everything else tends to work out someway

We have started the citizen science UAV flights- seems to be going well and picking up momentum now

Cheers

Dan

Daniel lerodiaconou Associate Professor VVVVV ><)))*> VVVVV School of Life and Environmental Sciences, Faculty of Science, Engineering and Built Environment Deakin University Warrnambool Campus, (room J314) Princes Hwy, Sherwood Park,Warrnambool, VIC 3280, Australia PH: +61409502980.





Sent: Turning, March 17, 2018 (100-4) Per Sent: Turning, March 17, 2018 (100-4) Per Sentime Parties Selection Factors

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Doeas that mean that private owners who flies UAV along the coast provide imagery to be collected and analysed ? that would be awesome, crowdsourced uav imagery to monitor coastal sedimentation !





Citizen Science + Drones



Training

Drone Set

Victoria Coast



- 14 groups
- Volunteers
- Locals



- Training
- Protocol



- DJI Phantom 4pro
- 10 Smart GCPs
- Tablet, batteries, spares









Data Quality + Validation

Data Quality and Validation







Professional Support



propeller

	X variance (mm)	Y variance (mm)	Z variance (mm)
count	58.000000	58.000000	58.00000
mean	6.815517	4.103448	7.934483
std	4.764555	4.739900	8.424620
min	0.400000	0.400000	0.700000
25%	4.350000	1.225000	3.375000
50%	6.200000	2.450000	5.850000
75%	8.150000	5.725000	9.875000
max	24.400000	27.900000	53.400000

- 58 Smart GCPs
- 2-3 hours acquisition time
- **7,4 and 8 mm** XYZ variance during GCP acquisition time



Quality Check

Images	median of 37454 keypoints per image	0
? Dataset	1073 out of 1109 images calibrated (96%), all images enabled	0
? Camera Optimization	0.49% relative difference between initial and optimized internal camera parameters	0
? Matching	median of 7556.25 matches per calibrated image	0
? Georeferencing	yes, 53 GCPs (53 3D), mean RMS error = 0.024 m	0

- Lady Bay, 1.6 km2 (161.6 ha)
- 2.4 cm RMSE 3D absolute accuracy
- 2.56 cm GSD \rightarrow 1 pixel of error

Data Quality and Validation





5

6

z_diff

0

2

3

tr_id

Data Quality and Validation

	fid	x	У	z_dsm	lateral rms	tr_id	z_rtk	new_field	z_diff
count	150.000000	150.000000	1.500000e+02	150.000000	150.000000	150.000000	150.000000	150.000000	150.000000
mean	109.673333	630516.725701	5.748889e+06	2.893818	0.004704	3.613333	2.937904	107.233333	-0.044086
std	68.745567	1139.485686	3.414026e+02	4.739371	0.001037	2.382224	4.750810	67.005300	0.077730
min	1.000000	628838.900500	5.748539e+06	-1.013198	0.002600	0.000000	-1.075440	1.000000	-0.514993
25%	39.250000	629083.574250	5.748563e+06	-0.138148	0.003925	1.000000	-0.095515	39.250000	-0.081568
50%	133.500000	631189.392150	5.748789e+06	0.770039	0.004700	5.000000	0.790380	129.500000	-0. <mark>0478</mark> 82
75%	170.750000	631634.218100	5.749270e+06	3.828357	0.005400	6.000000	3.946635	166.750000	-0.023891
max	208.000000	631679.697000	5.749501e+06	17.777303	0.008000	6.000000	17.797445	204.000000	0.141925



Mean Error (ME) = -0.04m (4cm)

 \rightarrow DSM values are slightly overestimated, but acceptable.

Root Mean Squared Error (RMSE) = 0.09m (9cm)

→ RMSE over PR method are known to overestimate the error estimations (Carrivick et.al, 2016).



Analysis + Communication

By the end of the **3 years** time Citizen Scientists will have produced more than **200 datasets** ...

... **14 locations** with differences in wind, wave and sediment regimes. **Good research** possibilities!

... there will be **1 Tb of DSM and** orthophotos to analyse ...

How to analyse such an amount of geospatial data in an efficient way?

PostgreSQL + PostGIS



Python Geospatial Scripting







Virtual Network of Elevation Profiles

Several hundreds virtual profiles will be monitoring the UAV sites at unprecedented accuracy.

Why elevation profiles?

- Convenience (data format and
- **Cut/Fill** observations \rightarrow seasonal? Storm-dependent?
- **Dynamic equilibrium?**
- Lack of wave data \rightarrow wind+profiles= wave conditions?





Marengo Beach

Beach length: 150 m Surveyed section: 170m **Orientation: EAST** Waves: avg 0.5m



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Marengo Beach

Beach length: 150 m Surveyed section: 170m **Orientation: EAST** Waves: avg 0.5m





Ongoing + Future

- Postgres database population
- Filtering of elevation points based on colour class (Callow et al., 2018)
- Volumetric analysis (DoDs) into database
- Getting better notebooks for Citizen Science distribution

Thank You

npucino@deakin.edu.au

Acknowledgment DELWP ANZGG Grant for Postgraduate Student









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